

FoMP: Vectors, Tensors and Fields 2009/2010

Problem Sheet 6: eigenvectors and diagonalisation of tensors

- 6.1 Three uniform rods of masses m , m , and $2m$ and lengths $2a$, $2a$ and $4a$ lie along the orthogonal axes Ox_1 , Ox_2 and Ox_3 respectively, with one end of each at O . Find the inertia tensor of the system at O , and also at the centre of mass G , referred to axes parallel to Ox_1 , Ox_2 and Ox_3 . Verify that the direction $(1, -1, 0)$ is a principal axis of inertia at G , and find the corresponding moment of inertia.
- 6.2 A molecule consists of two particles of mass m placed at vector positions (a, a, a) and $(-a, -a, -a)$ relative to an origin O . Show that the inertia tensor is

$$\underline{\underline{I}}(O) = 2ma^2 \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix}.$$

Calculate the eigenvalues and eigenvectors of this inertia tensor, and use symmetry arguments to interpret your results.

- 6.3 A symmetric second-rank tensor $\underline{\underline{T}}$ has components $T_{ij} = a_i b_j + b_i a_j$ in a particular basis, where a_i and b_i are components of the *unit* vectors $\underline{a}$ and $\underline{b}$.
- (i) By calculating $T_{ij}a_j$ and $T_{ij}b_j$, deduce that $\underline{a}$ and $\underline{b}$ are *not* eigenvectors of T . [*i.e.* $T_{ij}a_j \neq (\text{constant})a_i$, *etc.*]
 - (ii) Deduce that $(\underline{a} + \underline{b})$ and $(\underline{a} - \underline{b})$ are eigenvectors of T , with eigenvalues $(\cos \theta \pm 1)$, where θ is the angle between $\underline{a}$ and $\underline{b}$.
 - (iii) Verify that $\underline{c} = \underline{a} \times \underline{b}$ is also an eigenvector of T , and find its eigenvalue.
 - (iv) Check that the sum of the eigenvalues is the trace of T_{ij} .

- 6.4 (i) Find all eigenvalues and the corresponding set of (orthonormal) eigenvectors of the tensor

$$\underline{\underline{T}} = \begin{pmatrix} 4 & 1 & 1 \\ 1 & 4 & -1 \\ 1 & -1 & 2 \end{pmatrix}.$$

Do the eigenvectors form a left-handed or right-handed basis?

- (ii) If your eigenvectors form a right-handed (left-handed) basis, how can you transform them into a left-handed (right-handed) basis?
- (iii) Use the eigenvectors of a right-handed basis to write down the transformation matrix $\underline{\underline{\lambda}}$ that diagonalizes $\underline{\underline{T}}$.