

# FoMP: Vectors, Tensors and Fields 2009/2010

## Problem Sheet 3: suffix notation, summation convention and change of basis

- 3.1 Simplify the following expressions, where  $\delta_{ij}$  is the Kronecker delta symbol. The summation convention is implied.
- (i)  $A_i \delta_{ij}$ ; (ii)  $A_i B_j \delta_{ij}$ ; (iii)  $\delta_{ij} \delta_{jk}$ ; (iv)  $\delta_{ij} \delta_{jk} \delta_{kl}$ ; (v)  $A_i B_j C_k D_\ell \delta_{ij} \delta_{kl}$
- 3.2 A set of right-handed orthonormal basis vectors obeys the relation  $\underline{e}_i \times \underline{e}_j = \epsilon_{ijk} \underline{e}_k$ : show that this definition is consistent with the usual  $xyz$  coordinate system, and in particular that the basis vectors obey a cyclic pattern  $\underline{e}_1 \times \underline{e}_2 = \underline{e}_3$  etc.
- (a) Hence derive the components of the vector product:  $(\underline{A} \times \underline{B})_k = \epsilon_{ijk} A_i B_j$ .
- (b) Hence re-express the scalar triple product:  $\underline{C} \cdot (\underline{A} \times \underline{B}) = \epsilon_{ijk} A_i B_j C_k$ .
- 3.3 Verify that the definition  $\det M \equiv M_{1p} M_{2q} M_{3r} \epsilon_{pqr}$  correctly gives the determinant of  $\underline{\underline{M}}$ , an arbitrary  $3 \times 3$  matrix (remember to assume the summation convention).
- 3.4 The two sets of basis vectors  $\{\underline{e}_i\}$  and  $\{\underline{e}_i'\}$  are both right-handed orthonormal triads such that  $\underline{e}_1'$  is in the direction of  $(\underline{e}_1 + 2\underline{e}_3)$  and  $\underline{e}_2'$  is in the direction of  $(2\underline{e}_1 + \underline{e}_2 - \underline{e}_3)$ .
- (i) Construct the correctly normalised basis vectors  $\underline{e}_1', \underline{e}_2', \underline{e}_3'$ .
- (ii) Write down the transformation matrix  $\underline{\underline{\lambda}}$  from the basis  $\{\underline{e}_i\}$  to the basis  $\{\underline{e}_i'\}$ .
- (iii) The vector  $\underline{A}$  has components  $(1, 2, 3)$  in the original basis; the vector  $\underline{B}$  has components  $(1, 2, 3)$  in the *new* basis. For each vector, deduce components in both bases, and hence show directly that  $\underline{A} \cdot \underline{B}$  is unchanged by the transformation.